PROBABILISTIC ANALYSIS OF THE MAXIMAL LOAD OF INDUSTRIAL MACHINES

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This study describes the statistical analysis of peak forces of industrial washing machines. The data source comes from twelve different machines. The measurements are done using a force gauge installed in places for fastening screws. A new software based on LabView has been developed to gauge the acting forces. To determine extreme force values, various probability distributions are applied. Furthermore, a convex combination of lognormal distribution is used in more complicated cases. The parameters of the lognormal mixtures are determined using modified an Expectation-maximization algorithm. Finally, the achieved results are interpreted with regard to the engineering design and to the operating reliability. KEYWORDS

Washing machine, measurements, force, distribution, probability.

1 INTRODUCTION

During the operation process of industrial machines, the components of the machine are loaded with several operational forces. In the case of an industrial washing machine the operational load on the ground must be considered during the installation of the machine. The load is a combination of a static weight and dynamic forces. The dynamic load is mainly caused by the positioning of the laundry and its disbalance.



Figure 1. Typical industrial washing machine during measurement

Throughout the duration of the washing process the entire force cycle is evaluated with the maximum value. The aim of this paper is to quantify the properties of the maximal values.

The building structures are technically limited to a maximum load and a maximum floor deflection. So that knowledge of maximal forces is crucial for the correct positioning of the machines. Therefore, our industry partner must provide the maximal loading force in the technical parameters of the product. To solve the problem, we need to choose an appropriate distribution to describe the data. Another objective is to determine the minimum number of measurements that brings about quality results.

The problem of modelling and estimating the extreme value was presented in [Cole 2001, Folta 2012, Kracik 2013]. Generally, the usage of ordinary continuous distribution is sufficient for modelling extreme values [Cole 2001]. However, in some cases there is needed to apply a mixture distribution model [MCLachlan 2000]. In many cases there can be effectively used the mixture of normal distribution [McLahan 2000, Kracik 2013]. However, in modelling remote values the normal mixtures can be provided with many inaccuracies [Klemenc 2000]. Thus we present an alternative approach. We use a mixture of lognormal distributions instead of normal distributions. To estimate the parameters of the lognormal mixture we use the Expectation-Maximization (EM) algorithm [Dempster 1977, McLahlan 2000]. A modification of the EM algorithm will be briefly presented in this study.

2 DETERMINING THE NUMBER OF DATA

It is recommended to analyse at least 30 measurements in a standard data analysis. However, for determining higher quantile values it was necessary to use a larger data source [Cole 2001]. A simulation test was done to estimate the appropriate number of data. It randomly generated 3000 data sets (thousand per every distribution), each one with 1000 values with Weibull, Lognormal or Extreme-Value distribution. Thereafter there was randomly chosen from 40 to 100 measurements from every generated set. Finally, quantiles of generated sets and 40-100 values subsets were compared. It computed the relative frequency of the quantiles which did not overestimate the real value of the quantile. The results are presented in Table 1. According to Table 1 we can conclude that the minimal number of data is 100.

	Amount of measurements				
Quantile	40	60	80	100	
0.9	0.9	1	1	1	
0.91	0.90	1	1	1	
0.92	0.9	1	1	1	
0.93	0.89	1	1	1	
0.94	0.88	1	1	1	
0.95	0.88	0.99	1	1	
0.96	0.8	0.96	1	1	
0.97	0.79	0.98	1	1	
0.98	0.7	0.92	0.99	1	
0.99	0.67	0.91	3	1	
0.995	0.61	0.91	1	1	
0.999	0.52	0.90	0.94	0.99	

Table 1. Reliability of quantile estimate

3 PROCESS MEASUREMENT

For correctly estimating the probable maximum it was need to conduct at least a hundred measurements per machine. Since repeated measurements of wash cycles, with the participation of technicians is ineffective, new software (presented in Figure 2) was developed to measure the process. According to experience from the previous measurements, the maximum values were measured only in the loosening and centrifugation mode because the dynamic effects of those modes are always significantly higher than during the washing process.





The software was developed to measure the occurrence of peak values with the following characteristics:

- After obtaining the signal that the spinning and spinning mode is started, the software starts recording the force values acting on the floor from four different sensors located at the corners of the washing machine. The total vertical force was finally calculated as a sum of all four values.
- Software regularly evaluates the partial maximum value, and saves it in its memory. If the new value is larger than the previous value, it records this value as the maximum of the cycle.
- After finishing the spin cycle, the maximal values are saved -4 for each force sensor and one for the sum of the forces. Figures 4 and 6 present examples of the total maximum for washing machines per 36 kg of laundry and 70 kg of linen).
- Parallelly a set of local three-second maxima is created, which serves for the checking the remote values. It detects a possible electrical signal error (Figures 3 and 5).
- Finally, we obtain a database of maxims measured over the chosen time period, which can be statistically analysed in the form of histograms.



Figure 3. Record of partial maxima for one washing cycle – machine per 36 kg



Figure 4. Maximums in separate washing cycles – machine per 36 kg



Figure 5. Record of partial maxima for one washing cycle – machine per 70 kg



Figure 6. Maxima of separate washing cycles – machine per 70 kg

4 PROBLEM FORMULATION

The aim of this paper is to present an analysis of industry washing machines. Nineteen different machines were analysed in the presented research. We focused on determining the probability of the higher values of operational forces, at the request of an industrial partner. Generally, the task corresponds to the search for higher quantile values. Since the number of measurements is about one hundred per machine, the data sources could not be analysed as the discrete variable. Therefore, the data files were approximated by various continuous probability distributions. The parameters of the used distributions were determined using a maximal likelihood approach. The distribution suitability was tested by the chisquare test and the Kolmogorov-Smirnov test. Three different distributions were used to describe the data sufficiently. In one case a convex mixture of lognormal distribution was used (see the table below). The parameters of the lognormal mixture were estimated using a modified Expectation-Maximization (EM) algorithm.

Distribution	Number of applications		
Weibull	8		
Lognormal	5		
Extreme value	5		
Lognormal mixture	1		

Table 2. Number of used distributions EM algorithm

The EM algorithm is a method for finding the maximumlikelihood estimate of unknown parameters. The algorithm is an iterative method so that it converges with the local minimum of the likelihood function. The algorithm is applied to data with missing values (or it assumes the existence of missing data). The most used application of the algorithm is finding the parameters of mixture distribution. In this paper we have briefly presented a modification of the algorithm for finding the parameters of the mixture of lognormal distributions.

The algorithm consists of two steps E-stem (Expectation-step) and M-step (Maximization-step). It assumes the existence of observed data X and unobserved data Y.

E-step: In this step the algorithm computes the conditional expected value of the logarithmic log-likelihood function with respect to the parameter θ^j of the jth iteration and X.

$$q_{J+1}(\Theta) = E_{\Theta} \left[\log L(\theta | X, Y) | X, \theta^{j} \right]$$
(1)

• M-step: In this step the algorithm finds the θ^{j+1} that maximizes the expectation computed in the first step. $\Theta_{i+1} = \operatorname{argmax} q_{i+1}(\Theta)$ (2)

Now we present the EM algorithm for estimating the parameters of mixture distributions. A mixture distribution can be described by the following formula

$$f(x|\Theta) = \sum_{c=1}^{C} \alpha_c f(x|\theta_c)$$
(3)

where

 $\alpha_1, \alpha_2, \dots, \alpha_C$ are nonnegative real numbers such that

 $\sum_{c=1}^{C} \alpha_c = 1,$

 $f(x|\theta_c)$ is the distribution of cth component

 $\Theta = (\alpha_1, \alpha_2, \dots, \alpha_C, \theta_1, \theta_2, \dots, \theta_C)$ is the vector of estimated parameters of the mixture model.

After a series of technical adjustments, the E-step can be rewritten in the following form: q = (Q)

$$\begin{aligned} q_{J+1}(\Theta) &= \sum_{c=1}^{C} \sum_{i=1}^{N} \log(\alpha_c) f(c | x_i, \Theta^j) \\ &+ \sum_{c=1}^{C} \sum_{i=1}^{N} \log(f(x_i | \theta_c)) f(c | x_i, \Theta^j) \end{aligned}$$
(4)

Using the former expression, we can maximize α_c , θ_c from the form (1) independently.

Optimizing the first addition by applying the Lagrange multiplier we obtain an estimate of α_c .

Substituting the density of the lognormal distribution with parameters μ_c , σ_c we rewrite the right part of the formula as:

$$\sum_{c=1}^{C} \sum_{\substack{i=1\\C}}^{N} \log(f(x_{i}|\theta_{c})) f(c|x_{i},\theta^{j})$$
$$= \sum_{c=1}^{C} \sum_{\substack{i=1\\C}}^{N} \log\left(\frac{1}{x_{i}\sigma_{c}\sqrt{2\pi}} e^{-\frac{(\ln x_{i}-\mu_{c})^{2}}{2(\sigma_{c})^{2}}}\right) f(c|x_{i},\mu^{j},\sigma^{j})$$
(5)

Taking the derivative with respect to μ_c, σ_c , we obtain the maximal likelihood estimate of $\mu_c^{j+1}, \sigma_c^{j+1}$.

Generally, the maximal likelihood estimate of unknown parameters off lognormal mixture distribution of j + 1th iteration takes the form:

$$\alpha_{c}^{j+1} = \frac{1}{N} \sum_{i=1}^{N} f(c | x_{i}, \mu_{c}^{j}, \sigma_{c}^{j})$$

$$\mu_{c}^{j+1} = \frac{\sum_{i=1}^{N} \log x_{i} f(c|x_{i}, \mu_{c}^{j}, \sigma_{c}^{j})}{\sum_{i=1}^{N} f(c|x_{i}, \mu_{c}^{j}, \sigma_{c}^{j})}$$
(7)

$$\left(\sigma_{c}^{j+1}\right)^{2} = \frac{\sum_{i=1}^{N} (\log x_{i} - \mu_{c}^{j+1}) f(c | x_{i}, \mu_{c}^{j}, \sigma_{c}^{j})}{\sum_{i=1}^{N} f(c | x_{i}, \mu_{c}^{j}, \sigma_{c}^{j})}$$
(8)

5 RESULTS

In this chapter we have presented four examples of analysed data. Every data source is described with a different distribution - Weibull, Lognormal, Extreme value and Gaussian mixture distribution. In the case of a widely used continuous distribution the appropriate distribution parameters were estimated using the maximum likelihood approach. The parameters of lognormal mixture distribution were estimated with the EM algorithm described above.

In next subchapters we will present the measured data, its histogram and the final evaluation of the probable maximum for different distributions. In Table 3 we describe summarized statistics of the presented data sets.

Text	Wbl.	Mix. Log	E.V.	Log.
count	100	110	95	150
mean	980	2180	1050	1405
median	1000	2155	960	1480
max	1305	1305	1300	2155
Std.	91	102	106	263.1
q. 0.99	1301	2340	1261	1920
q. 0.999	1320	2380	1342	2100

 Table 3. Summary statistics

5.1 Weibull Distribution

This distribution function was used to evaluate a washing machine with a load of 36 kg of laundry and for evaluating the centrifugation cycle only for a maximum speed. The graphical results are presented in Figures 7-9.







Figure 8. Histogram of maxima from Fig. 7

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(6)



Figure 9. Estimation of the maximum force for different probability of occurrence for Weibull distribution

5.2 Lognormal Mixture Distribution

This distribution function was used to evaluate a washing machine with a load of 36 kg of laundry and for evaluating the entire centrifugation cycle. The graphical results are presented in Figures 10-12.



Figure 10. Maximums in separate washing cycles



Figure 11. Histogram of maxima from Fig. 10



Figure 12. Estimation of the maximum force for different probability of occurrence for Lognormal Mixture distribution

5.3 Extreme value

This distribution function was used to evaluate a washing machine with a load of 50 kg of laundry and for evaluating the centrifugation cycle only for a maximum speed. The graphical results are presented in Figures 13-15.



Figure 13. Maximums in separate washing cycles



Figure 14. Histogram of maxima from Fig. 13



Figure 15. Estimation of the maximum force for different probability of occurrence for Extreme value distribution

5.4 Lognormal distribution

This distribution function was used to evaluate a washing machine with a load of 70 kg of laundry and for evaluating the entire centrifugation cycle. The graphical results are presented in Figures 16-18.



Figure 16. Maximums in separate washing cycles



Figure 17. Histogram of maxima from Fig. 16



Figure 18. Estimation of the maximum force for different probabilities of occurrence for Lognormal distribution

6 CONCLUSION

A statistical analysis of the maximal forces was presented in this study. Analyzed data were described using various continuous distributions – Weibull, Extreme value and Lognormal distribution. The last row of Table 3 shows the resulting values of the probable maximum value for 99.9%. These data suggest the need for a proper analysis of the type of probability

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distribution, because using the wrong distribution can lead to incorrect results.

In one case it was necessary to use a convex combination of lognormal distributions. The parameters were estimated using a modified EM algorithm. Since we are describing the extreme values, the lognormal mixture modelling is further more effective than the more often used normal mixture distribution. This technique can be applied in a wide area of statistical analysis and applications.

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